STÄHLE

Robot Shifter AP-SA

for manual and automatic transmissions







Descriptions

The Robot Shifter AP-SA consists of two closed loop position controlled servo electric actuators for shift operations for both, manual transmission and automatic transmission.

- Operation with handy terminal
- Teach in procedure to learn the gear positions with the handy terminal
- Limitation of the shift torque by limiting the DC motor current
- Different parameter sets with definitions of shift arm velocities
- Position monitoring of all gear positions
- Shift error repetitions with strategies to solve "tooth-on-tooth" conditions of the transmission
- DC motors are disabled after each completed shift operation
- Manual shift operation mode via handy terminal
- Manual transmission: max. 8 gears + neutral + reverse gear
- Automatic transmission: P/R/N/D/5/4/3/2/1/M/+/- in any sequence

Specifications

Actuator system electrically Motion spherical Shift stroke (X-axis lateral) max. 200 mm Shift stroke (Y-axis longitudinal) max. 250 mm max. 250 N Shift force Velocity max. 0.6 m/s

Position measuring conductive plastic potentiometer

Measurement accuracy 0.09mm 24VDC Motor voltage

-30°C ... +80°C Operating temperature

Content of delivery

- Shift actuator Stand Alone
- Shift arm with stick handle and adapter sleeves
- Power controller 19"/3 HE, 115/230VAC, 500W
- Cable set Computer system <-> Power controller, 1m
- Cable set Power controller <-> actuator system, 10m
- Industrial-PC 19"
- Handy terminal with 8x40 Display, backlighted

Options

- Shift force measurement and closed loop shift force control
- Gear shift release mechanism
- Interface to electrical, position controlled clutch actuators. for example AP-K.00
- Host computer interfaces
 - Serial or TCP/IP: Extended AK protocol
 - TCP/IP: OPC Server / Client
 - Hybrid bit parallel & analog interface
- Fieldbus Interfaces



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